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Azimuth Position Control System  
Antenna Potentiometer Fixed field  $e_m(t)$   
Armature Gear Layout Potentiometer  
 $e_i(t)$  Desired azimuth angle input  
Differential amplifier and power  
amplifier Motor Schematic Desired  
azimuth angle input  $e_i(t)$  n-turn  
potentiometer 80 (t) Azimuth angle

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output Differential preamplifier Power  
amplifier  $v_p(t)$   $e_a(t)$   $V_i(t) + v_o(t)$  — kg-  
m<sup>2</sup> N-m s/rad V-s/rad N-m/A n-turn  
potentiometer Azimuth angle output  $e_o$   
...

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